Ajay Gunalan Ph.D.

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It's Not Possible. No, It's Necessary.

I love the thrill of developing cutting-edge tech by fusing multiple disciplines and collaborating in a diverse team.

EDUCATION

ITALIAN INSTITUTE OF TECHNOLOGY & UNIVERSITY OF GENOA

Ph.D. in Bioengineering and Robotics

Genoa, Italy Nov 2020 - March 2024

B.S.A. Crescent Institute of Science and Technology

B.Tech. in Mechanical Engineering | CGPA: 8.45/10.00

Chennai, India Aug 2013 - May 2017

G.R.T Mahalakshmi Vidyalaya

12th Grade | 88.0%

Chennai, India Mar 2013

A.V. MEIYAPPAN MATRICULATION 10th Grade | 87.4%

Chennai, India Mar 2011

SUMMARY & SKILLS

- 3 years of experience in computational imaging, image processing, inverse problems, machine learning, interferometry and optics (YouTube Link)

- 3 years of experience in robotic software development, multi-threading, ROS, communication protocols and signal processing with a strong foundation in data structures and algorithms. (LeetCode)

Programming Languages

C, C++, Python, MATLAB, LATEX

Libraries & Frameworks Embedded Systems

OpenCV, PyTorch, CUDA, ROS, MoveIt, git, Make, CMake

Arduino, STM32F4, Embedded Linux

EXPERIENCE

ITALIAN INSTITUTE OF TECHNOLOGY

Ph.D. Student

Genoa, Italy Nov 2020 - April 2024

Computational Sensing for ISM & OCT Guided Laser Microsurgery.

- Towards OCT-Guided Endoscopic Laser Surgery—A Review (pub.)
- Compressive Image Scanning Microscope. (code, pub.)
- Compressive 3D OCT-Guided Laser Microsurgery. (in-preparation)
- Autonomous Computer-Assisted Laser Microsurgery. (accepted, video)

ITALIAN INSTITUTE OF TECHNOLOGY

Genoa, Italy

C++ Software Engineer

Oct 2019 - Oct 2020

Interfaced multiple real-sense, zed & other sensors with Nvidia jetson to stream audio, video & pointcloud simultaneously in virtual reality (VR) for tele-operated robots by multi-threading. (LOR, blog)

ROBERT BOSCH CENTRE FOR CYBER PHYSICAL SYSTEMS, IISC Software Engineer

Bangalore, India Feb 2018 - Jun 2019

(1) Motion planning simulation of a robotic arm in Gazebo using ROS and MoveIt; (2) CAN bus communication between two linux system; (3) Software development for servo motor control and trajectory tracking for quadruped robot; (4) Improved the communication rate between low-level drivers and control algorithms by shared-memory (IPC); (5) Control the robot like in a video game using non-blocking communication (blog, pub.)

ASIMOV ROBOTICS PVT. LTD.

Kochi, India

Software Engineer Internship

Jul 2017 - Dec 2017

(1) Gravity compensation for a banking service robot; (2) Position and velocity control of DC motor; (3) TCP/IP communication between ROS and non-ROS module; (4) Sensors like IMU, etc. integration using I2C & SPI. (blog)

SELECTED AWARDS

- Finalist, Top 10 out of 11,000+ applicants, in IICDC 2016 by Texas Instruments Inc. & Indian Institute of Management, Bangalore for our medical device, "Smart Intravenous Dripper". (blog)

OTHER DETAILS

- Publication: Google Scholar
- Online Courses: First Order Optical System Design by University of Colorado Boulder. (link)
- Citizenship/DOB: Indian/December 20, 1995

PUBLICATIONS

- 1. A. Gunalan et al. "Compressive 3D OCT-Guided Laser Microsurgery". (in-preparation)
- 2. S. Li, A. Gunalan et al. "Auto-CALM: Autonomous Computer-Assisted Laser Microsurgery," to IEEE Transactions on Medical Robotics and Bionics. (accepted) [video]
- 3. A. Gunalan et al. "Compressive Image Scanning Microscope," In: International Symposium on Computational Sensing, Luxembourg, 2023. [link]
- 4. **A. Gunalan**, L. S. Mattos, "Towards OCT-Guided Endoscopic Laser Surgery—A Review," Diagnostics, 2023. [link]
- 5. S. Li, M.A. Azam, A. Gunalan, et al. "One-Step Enhancer: Deblurring and Denoising of OCT Images", Applied Sciences, 2022. [link]
- 6. D. Dholakiya, S. Bhattacharya, A. Gunalan, et al. "Design, Development and Experimental Realization of a Quadrupedal Research Platform: Stoch". In:IEEE International Conference on Control Automation and Robotics (ICCAR), 2019. [link]

RELEVANT PH.D. COURSEWORK

- 1. Nanophotonic Devices: From Fabrication to Applications by Andrea Toma, IIT, Italy.
- 2. Electronics and Circuits by Marco Sartore, University of Genoa, Italy.
- 3. Advanced Optical Fluorescence Microscopy Methods by Paolo Bianchini, IIT, Italy.

MISCELLANEOUS

- Took seminars on simulation of a robotic arm in Gazebo using ROS and MoveIt for students of Dr. Shishir Kolathaya and Prof. Ashitav Goshal at IISc, Bangalore [link].
- Internship (July 2016) at TIDC INDIA, Ambattur, India, where I learnt various process and methodologies involved in desgin and fabrication of cam chain used in two-wheelers.
- Internship (June 2016) at J.K. Fenner(India) Ltd, Sriperumbudur, India, where I learnt various process and methodologies involved in desgin and fabrication of rubber seal's used in bearings.
- Inplant Training (June 2015) at Ashok Leyland, Ennore, India, where I had a practical exposure to various manufacturing methods and assemble line production system.

REFEREES

- 1. Dr. Leonardo De Mattos Italian Institute of Technology
- 2. Dr. Nikhil Deshpande University of Nottingham
- 3. Dr. Veronica Penza Italian Institute of Technology

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